This is a closed-book closed-notes no-calculator-allowed in-class exam. Efforts have been made to keep the arithmetic simple. If it turns out to be complicated, that's either because I made a mistake or you did. In either case, do the best you can and check your work where possible. While getting the right answer is nice, this is not an arithmetic test. It's more important to clearly explain what you did and what you know.

1. Indicate in writing that you have understood the requirement to work independently by writing "I have worked independently on this exam" followed by your signature as the answer to this question.

**2.** Consider the matrix A with inverse  $A^{-1}$  given by

$$A = \begin{bmatrix} -1 & -2 & 0 & 0 \\ 1 & -1 & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & 0 & 0 & 1 \\ 0 & \frac{1}{2} & 0 & -1 \end{bmatrix} \quad \text{and} \quad A^{-1} = \begin{bmatrix} -\frac{1}{3} & 0 & -\frac{4}{3} & -\frac{4}{3} \\ -\frac{1}{3} & 0 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{6} & -2 & -\frac{11}{3} & -\frac{14}{3} \\ -\frac{1}{6} & 0 & \frac{1}{3} & -\frac{2}{3} \end{bmatrix}.$$
all that the matrix 1-norm of  $A$  may be computed as

Recall that the matrix 1-norm of A may be computed as

$$\|A\|_1 = \max \Big\{ \sum_{i=1}^n |A_{ik}| : k=1,\dots,n \Big\} \quad \text{where} \quad n=4.$$
 Compute  $\|A\|_1$  and  $\|A^{-1}\|_1$  and then use the 1-norm to find  $\operatorname{cond}(A)$ .

$$\|A\|_{1} = \max \{ \lambda_{2}, 3\frac{1}{2}, \frac{1}{2}, \frac{1}{2} \} = 3\frac{1}{2} = \frac{2}{2}$$
  
 $\|A^{4}\|_{1} = \max \{ 1, a, \frac{18}{3}, \frac{22}{3} \} = \frac{2a}{3}$ 

Math 466/666: Midterm Version A

**3.** Let  $f: \mathbf{R} \to \mathbf{R}$  be a twice continuously differentiable function such that  $f(\alpha) = 0$  and  $f'(\alpha) \neq 0$ . Explain why Newton's method, given by

$$x_{n+1} = x_n - \frac{f(x)}{f'(x)}$$
 where  $x_0$  is an initial approximation

is quadratically convergent. That is, provided  $x_0$  is sufficiently close to  $\alpha$  prove there exists a constant M such that

$$|e_{n+1}| \le M|e_n|^2$$
 where  $e_n = x_n - \alpha$  for  $n = 0, 1, 2, \dots$ 

By Taylor's theorem

$$D = f(x) = f(x_n - e_n) = f(x_n) - e_n f'(x_n) + \frac{e_n^2}{2} f''(\xi_n)$$
where  $\xi_n$  is between  $x_n$  and  $\alpha$ .

Thus, dividing by 
$$f(x_n)$$
 yields
$$6 = \left(\frac{f(x_n)}{f'(x_n)}\right) - e_n + \frac{e_n^2}{2} \frac{f''(\xi_n)}{f'(\xi_n)}$$

Chair det of entry  $C_{n+1} = 2C_{n+1} - d = I_n - \frac{f(x_n)}{f'(x_n)} - d = e_n - \frac{f(x_n)}{f'(x_n)}$ by Taylor  $C_n - e_n^2 \frac{f''(\xi_n)}{f'(x_n)} = \frac{f'''(\xi_n)}{2f'(x_n)}e_n^2$ The only thing left is to bound by a constant...

4. Explain why it is sometimes said the number of correct significant digits approximately doubles with each iteration when using Newton's method.

We have  $|e_{n+1}| \le M |e_n|^2$  suppose  $|e_n| \ge 10^{-k}$  thun  $|e_{n+1}| \le M (10^{-k})^2 = M \cdot 10^{-2k}$  Suppose  $M = 10^P$  thun  $|e_{n+1}| \le 10^{P-2k}$  it k is very big compared to p then  $P-1k \approx -2k$  and k world be very big efter the sequence has iterated for some time.

Proof of quadratic convergence of Newton's method continues
Since f(d) \$0 there is a d-neighborhood of K
such that $f'(\infty) \neq 0$ for all $ x-\alpha  \leq 8$ .
define $B = \min \{  f'(x)  :  x-x  \leq 8 \} > 0$
· · · · · · · · · · · · · · · · · · ·
For the same & define
A= max {   f"(x)   : pc-2   58 } < po
Therefore if $ x_n-a  \leq 8$ and $ x_n-a  \leq 8$ then
16 nx1   < A 16 n  2
Need to make Sure that lenn (< len) so that it
120-2/58 then also 121-0/58 and so forth
To do this not a that
lenn 1 ( A len len)
Ab .
Need Preed this less than I so the estimate
can propagate sorward
<del></del>
30 if xo is close enoughto & such that
30 17 20 13
$ x_0-x  < min\left(\delta, \frac{2B}{A}\right)$
then the Newton's method couverges quadratically
V

**5.** Given a unit vector  $v \in \mathbf{R}^n$  the corresponding Hausholder reflector is  $H = I - 2vv^T$ . Show that H is an orthogonal matrix.

Thus 
$$H^T = (I - 2vv^T)^T = I^T - (2vv^T)^T$$

$$= I^T - 2vv^Tv^T = I - 2vv^T$$
Thus  $H^T = H$  and  $H$  is symmetric...
$$H^T H = (I - 2vv^T)(I - 2vv^T) = I - 2vv^T - 2vv^T + 4v(v^Tv)^T$$

$$= I - 4vv^T + 4vv^T = I$$

**6.** Factor the matrix

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \qquad \begin{matrix} \mathbf{r_L - r_L - 3} \\ \mathbf{r_1} & \begin{matrix} \mathbf{r_1} \\ \mathbf{r_2} \end{matrix}$$

as A = LU where L is lower triangular and U is upper triangular.

Thus 
$$U = \begin{bmatrix} 1 & 2 \\ 0 & -2 \end{bmatrix}$$
 and  $L = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$ 

7. Consider a hypothetical computer which performs all arithmetic in decimal using round-to-the-nearest with 7 significant digits. Let x = 1.437592 and y = 1.431256. Find the value of z = x - y as calculated by the computer and explain how many digits of precision were lost when performing the calculation.

3 digits cancelled so 3 digits of prevision were lost.

8. If you are enrolled in Math 466 prove one of the following theorems; if you are enrolled in Math 666 prove both of them:

Proposition 6.3 All eigenvalues of Hermitian matrices are real.

Proposition 6.4 Eigenvectors corresponding to distinct eigenvalues of Hermitian matrices must be orthogonal.

## Proof of Proposition 6.3

Yet I be an eigenvalue with eigenvector oc

 $\int Ax = 3x$ . I real means  $J = \overline{\lambda}$ .

 $\bar{x} \cdot Ax = Ax \cdot \bar{x} = (Ax) \bar{x}$ 

 $= x^T A^T \bar{x} = x^T A^H \bar{x}$ 

= xT Ax = x. Ax

Thus

 $\bar{x} \cdot Ax = x \cdot Ax$ 

 $\tilde{x} \cdot \lambda x = x \cdot \lambda x$ 

 $\lambda \widetilde{\mathcal{X}} \times \mathcal{X} = \widetilde{\lambda} \times \widetilde{\mathcal{X}}$ 

 $\lambda = \overline{\lambda}$ 

2 is real ...

since XE. (), " is not zero, thun 20.5011 x 112

Troof of Prop 6.4 is on the back

## Proof of Prop 6.4 Let $Ax_1 = \lambda_1 x_1$ and $Ax_2 = \lambda_2 x_2$ and A=A. Note from Prop. 6.3 21, 2 ER Need to show: $x_1 \cdot \overline{x}_2 = 0$ since $x_1, x_2 \in \mathbb{C}^n$ $\bar{x} \cdot A x_a = A x_a \cdot \bar{x}_a = (A x_a) \cdot \bar{x}_a$ $= x_{1}^{T}A^{T}\bar{x}_{1} = x_{1}^{T}\overline{A^{H}}\bar{x}_{1}$ = xt Ax = x. Ax, Therefore $\overline{x}_1 \cdot Ax_2 = x_2 \cdot \overline{Ax_1}$ $\overline{x}_1 \cdot \lambda_2 x_2 \approx x_2 \cdot \overline{\lambda_1} x_1$ $\lambda_2 \overline{\chi}_1 \cdot \chi_2 = \overline{\lambda}_1 \chi_2 \cdot \overline{\chi}_1$ Since SieR then 2,=2, Thus, $(\lambda_2 - \lambda_1) \overline{\chi}_1 \cdot \chi_2 = 0$

Since  $\lambda_1 \pm \lambda_2$  then  $\overline{\mathfrak{IC}_1} \cdot \mathfrak{IC}_2 = 0$ ...