Math 330 Linear Algebra Homework 13

- **12.3** Least angle property of least squares. Suppose the $m \times n$ matrix A has linearly independent columns, and b is an m-vector. Let $\hat{x} = A^{\dagger}b$ denote the least squares approximate solution of Ax = b.
 - (a) Show that for any *n*-vector x, $(Ax)^Tb = (Ax)^T(A\hat{x})$, *i.e.*, the inner product of Ax and b is the same as the inner product of Ax and $A\hat{x}$. Hint. Use $(Ax)^Tb = x^T(A^Tb)$ and $(A^TA)\hat{x} = A^Tb$.
 - (b) Show that when $A\hat{x}$ and b are both nonzero, we have

$$\frac{(A\hat{x})^T b}{\|A\hat{x}\| \|b\|} = \frac{\|A\hat{x}\|}{\|b\|}.$$

The left-hand side is the cosine of the angle between $A\hat{x}$ and b. Hint. Apply part (a) with $x = \hat{x}$.

- (c) Least angle property of least squares. The choice $x = \hat{x}$ minimizes the distance between Ax and b. Show that $x = \hat{x}$ also minimizes the angle between Ax and b. (You can assume that Ax and b are nonzero.) Remark. For any positive scalar α , $x = \alpha \hat{x}$ also minimizes the angle between Ax and b.
- (a) compute $(Ax)^{T}(A\hat{x}) = (Ax)^{T}AA^{T}b = (Ax)^{T}A(A^{T}A)^{-1}A^{T}b$ $= x^{T}A^{T}A(A^{T}A)^{-1}A^{T}b = x^{T}A^{T}b$ $= (Ax)^{T}b$

(b) Setting $x = \hat{x}$ in the above identity yields $\begin{aligned}
&||A\hat{x}||^2 = (A\hat{x})^T b \\
&||Now|| & \text{dividing by } ||A\hat{x}|| |||b||| & \text{on both sides gives} \\
&||(A\hat{x})^T b|| &= ||A\hat{x}|| \\
&||A\hat{x}|| ||b||| &= ||A\hat{x}||
\end{aligned}$

#12.3 continues ...

(c) Since cosine is a decreasing function of angle on the interval [0, The then showing x=x is the choice which minimizes the angle between An and b is equivalent to showing the choice x= 2 maximizes the cosine of the angle between Ax and b.

The wrine of the angle between An and b is given by

 $(Ax)^Tb$ 11Ax11 116/1

Estimating by Cauchy-Schwarz inequality yields

 $\frac{(Ax)^Tb}{(Ax)^T} = \frac{(Ax)^T(Ax)}{(Ax)} \leq \frac{\|Ax(1)\|Ax(1)\|}{(Ax)^T}$ 1/4/1/11/6/1 11Ax1111611 11Ax111611

 $= \frac{\|A\hat{x}\|}{\|A\hat{x}\|} = \frac{(A\hat{x})^T h}{\|A\hat{x}\|^T h}$

which is the cosine of the angle between 4% and b. Therefore we have shown that x=2 is the choice which minimizes the angle between 4x and b.

12.5 Approximate right inverse. Suppose the tall $m \times n$ matrix A has linearly independent columns. It does not have a right inverse, i.e., there is no $n \times m$ matrix X for which AX = I. So instead we seek the $n \times m$ matrix X for which the residual matrix R = AX - I has the smallest possible matrix norm. We call this matrix the least squares approximate right inverse of A. Show that the least squares right inverse of A is given by $X = A^{\dagger}$. Hint. This is a matrix least squares problem; see page 233.

Since 11R112=11AX-I1/2 =1/Ax,-e,1/2+ ... + 1/Axm-em/12

where xi's are the columns of X and ci's are the standard basis vectors in RM, we can minimize R by finding the minimum of MAX; - eil for i=1,..., m independently. To minimize MAX; -eil we note that $\hat{x}_i = A^{\dagger}e_i$. Therefore the minimizing matrix \hat{x} is given by.

 $\hat{X} = \left| \frac{\hat{x}_1}{\hat{x}_2} \right| \frac{\hat{x}_m}{\hat{x}_m} = \left| \frac{A^{\dagger} e_1}{A^{\dagger} e_2} \right| \dots \left| \frac{A^{\dagger} e_m}{A^{\dagger} e_m} \right|$ $= A^{\dagger} \left| \frac{e_1}{e_2} \right| \frac{e_2}{m} \left| \frac{e_m}{e_m} \right| = A^{\dagger} I = A^{\dagger}.$

- 12.8 Least squares and QR factorization. Suppose A is an $m \times n$ matrix with linearly independent columns and QR factorization A = QR, and b is an m-vector. The vector $A\hat{x}$ is the linear combination of the columns of A that is closest to the vector b, *i.e.*, it is the projection of b onto the set of linear combinations of the columns of A.
 - (a) Show that $A\hat{x} = QQ^Tb$. (The matrix QQ^T is called the projection matrix.)
 - (b) Show that $||A\hat{x}-b||^2 = ||b||^2 ||Q^Tb||^2$. (This is the square of the distance between b and the closest linear combination of the columns of A.)

and the closest linear combination of the columns of A.)

(a) By definition
$$\hat{x} = A^{\dagger}b = (A^{\dagger}A)^{-1}A^{\dagger}b$$
. Plugging in the QR factorization yields that $\hat{x} = ((QR)^{\dagger}QR)^{*}(QR)^{\dagger}b = (R^{\dagger}Q^{\dagger}QR)^{-1}R^{\dagger}Q^{\dagger}b$

$$= (R^{\dagger}R)^{-1}R^{\dagger}Q^{\dagger}b$$
and since R is invertible, then

 $\hat{\chi} = R^{-1}(R^T)^{-1}R^TQ^Tb = R^{-1}Q^Tb.$

It follows that

An = ARTaTb = QRRTQTh = QQTb.

(6) Calculating yields
$$||A\hat{x}-b||^2 = ||AR^Tb-b||^2 = (QR^Tb-b)^T (QR^Tb-b)$$

$$= (QR^Tb)^T QR^Tb-b^T QR^Tb-(QR^Tb)^Tb+b^Tb$$

$$= b^T QR^T QR^Tb-2b^T QR^Tb+b^Tb$$

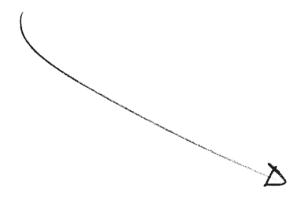
$$= -b^T QR^Tb+b^Tb = ||b||^2 - (Q^Tb)^T Q^Tb$$

$$-||b||^2 - ||Q^Tb||^2.$$

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12.10 Numerical check of the least squares approximate solution. Generate a random 30×10 matrix A and a random 30-vector b. Compute the least squares approximate solution $\hat{x} = A^{\dagger}b$ and the associated residual norm squared $||A\hat{x} - b||^2$. (There may be several ways to do this, depending on the software package you use.) Generate three different random 10-vectors d_1, d_2, d_3 , and verify that $||A(\hat{x} + d_i) - b||^2 > ||A\hat{x} - b||^2$ holds. (This shows that $x = \hat{x}$ has a smaller associated residual than the choices $x = \hat{x} + d_i$, i = 1, 2, 3.)

Solution is in Julia on the next page ...



hw13p1210

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Homework 13 Question 12.10

```
[18]: using LinearAlgebra
[19]: A=rand(30,10);
      b=rand(30);
[20]:
     Adagger=inv(A'*A)*A';
[21]:
      xhat=Adagger*b;
[22]:
     norm(A*xhat-b)
[22]: 1.494082025485521
[23]: d1=rand(10);
      d2=rand(10);
      d3=rand(10);
[24]: norm(A*(xhat+d1)-b)
[24]: 15.498057939880987
     norm(A*(xhat+d2)-b)
[25]:
[25]: 14.142275011244568
     norm(A*(xhat+d3)-b)
[26]:
[26]: 14.427812725660111
```

Note in each of these cases that

$$||A(\hat{x}-d_i)-b|| > ||A\hat{x}-b||.$$

We try again with random vectors d_i with smaller norms as the random vectors chosen above are relatively large compared to the least squares solution \tilde{x} .

```
[27]: d1=1e-6*rand(10);
d2=1e-6*rand(10);
d3=1e-6*rand(10);
```

We then compute

$$||A(\hat{x}-d_i)-b||-||A\hat{x}-b||$$

for each value of i and check that this difference is positive.

```
[28]: norm(A*(xhat+d1)-b)-norm(A*xhat-b)
```

[28]: 3.779554447191913e-11

```
[29]: norm(A*(xhat+d2)-b)-norm(A*xhat-b)
```

[29]: 1.3354650718611083e-10

```
[30]: norm(A*(xhat+d3)-b)-norm(A*xhat-b)
```

[30]: 6.07782713046845e-11

Though small, each of the differences are positive. This constitutes a numerical verification of the least squares approximate solution.